

Course web page: http://goo.gl/EB3aA



April 10, 2012 * Lecture 15

Outline

- Global illumination with ray casting & ray tracing
- Ray casting
 - Intersections
 - Shadow rays



Illumination models

- Interaction between light sources and objects in scene that results in perception of intensity and color at eye
- Local vs. global models
 - Local illumination: Perception of a particular primitive only depends on light sources **directly** affecting that one primitive
 - Geometry
 - Material properties
 - Global illumination: Also take into account indirect effects on light of other objects in the scene
 - Shadows cast
 - Light reflected/refracted



"Forward" Ray Tracing

- Proper global illumination means simulation of physics of light
 - Rays are emitted from light source, bounce off objects in the scene, and some eventually hit our eye, forming an image
- Problem: Not many rays make it to the image
 - Waste of computation for those that don't





"Backward" Ray Tracing

 Idea: Only consider those rays that do create the image—where did they come from?





Backward Ray "Following": Types

- Ray casting: Compute illumination at first intersected surface point only
 - Takes care of hidden surface elimination
- **Ray tracing**: Recursively spawn rays at hit points to simulate reflection, refraction, etc.







Lighting a point

- Let c = (r, g, b) be perceived material color (called i on previous slides), s(l) be color of light /
- Sum over all lights / for each color channel (clamp overflow to [0, 1]):



$$\begin{aligned} \mathbf{c}_{total} &= \sum_{l} \mathbf{c}_{amb}(l) + \mathbf{c}_{diff}(l) + \mathbf{c}_{spec}(l) \\ \mathbf{c}_{amb}(l) &= \mathbf{m}_{amb} \otimes \mathbf{s}_{amb}(l) \\ \mathbf{c}_{diff}(l) &= \max(0, \mathbf{n} \cdot \mathbf{l}(l)) \mathbf{m}_{diff} \otimes \mathbf{s}_{diff}(l) \\ \mathbf{c}_{spec}(l) &= \max(0, \mathbf{v} \cdot \mathbf{r}(l))^{shine} \mathbf{m}_{spec} \otimes \mathbf{s}_{spec}(l) \end{aligned}$$

One of the earliest ray-traced scenes



from T. Whitted's paper

State of the art in 1980 (B & W reproduction of a color image)



Ray Tracing: Example





Ray Tracing: Example from "Cars"



http://www.sci.utah.edu/~wald/RT06/papers/raytracing06per.pdf



Ray Casting

- Simulation of irradiance (incoming light ray) at each pixel
- Send a ray from the focal point through each pixel and out into the scene and see if it intersects an object

"Background" color if nothing hit

- Local shading model is applied to **first** point hit
 - Easy to apply exact rather than faceted shading model to objects for which we have an analytic description (spheres, cones, cylinders, etc.)



Ray Casting: Details

• Must compute 3-D ray into scene for each 2-D image pixel (Chap. 4.3 of Shirley)



- Compute 3-D position of ray's intersection with nearest object and normal at that point
- Apply shading model such as Phong to get color at that point and fill in pixel with it





Does Ray Intersect any Scene Primitives?

- Test each primitive in scene for intersection individually
- Different methods for different kinds of primitives
 - Polygon
 - Sphere
 - Cylinder, torus
 - Etc.
- Make sure intersection point is in front of eye and nearest one





Ray-Sphere Intersection I

• Combine implicit definition of sphere $|\mathbf{p} - \mathbf{p}_c|^2 - r^2 = 0$

with ray equation

$$\mathbf{p} = \mathbf{o} + t\mathbf{d}$$

(where **d** is a unit vector) to get:

$$|\mathbf{o} + t\mathbf{d} - \mathbf{p}_c|^2 - r^2 = 0$$



Ray-Sphere Intersection II

• Substitute $\Delta p = p_c - o$ and use identity $|a + b|^2 = |a|^2 + 2a \cdot b + |b|^2$ to solve for t, resulting in a quadratic equation with roots given by:

$$t = \mathbf{d} \cdot \Delta \mathbf{p} \pm \sqrt{(\mathbf{d} \cdot \Delta \mathbf{p})^2 - (|\Delta \mathbf{p}|^2 - r^2)}$$

- Notes
 - Real solutions mean there actually are 1 or 2 intersections
 - Negative solutions are behind eye



Ray-Polygon Intersection

- General polygons
 - Express point **p** on a ray as some distance t along direction **d** from origin **o**: **p** = **o** + t**d**
 - Use plane equation $\mathbf{n} \cdot \mathbf{x} + d = 0$, substitute $\mathbf{o} + t\mathbf{d}$ for \mathbf{x} , and solve for t
 - Only positive t's mean the intersection is in front of the eye
 - Then plug t back into p = o + td to get p
 - Is the 2-D location of **p** on the plane inside the 2-D polygon?
 - For convex polys, Cohen-Sutherland-style outcode test will work
- Triangles
 - Direct barycentric coordinates expression (see Shirley, Chaps. 2.7 and 4.4)

$$\mathbf{t}(u,v) = (1-u-v)\mathbf{v}_0 + u\mathbf{v}_1 + v\mathbf{v}_2$$

- Set this equal to parametric form of ray $\mathbf{o} + t\mathbf{d}$ and solve for intersection point (t, u, v)
- Only inside triangle if u, v, and 1 u v are between 0 and 1



Shadow Rays

 For point being locally shaded, spawn new ray in each light direction and check for intersection to make sure light is "visible"





Shadow Rays

- For point p being locally shaded, only add diffuse & specular components for light I if light is not occluded (i.e., blocked)
- Test for occlusion of I for **p**:
 - Spawn **shadow ray** for I with origin **p**, direction I(I)
 - Check whether shadow ray intersects any scene object

- Intersection only "counts" if:

$$0 < t < |\mathbf{p}_l - \mathbf{p}|$$

• More details in Shirley, Chap. 4.7



Ray-Cast Scene with and without Shadows



from Hill



Ray Casting Example: No shadows





Light 1 only

Light 2 only







Ray Casting Examples: Shadows



Light 1 only

Light 2 only





Lights 1 and 2

Ambient Occlusion

- Extension of shadow ray idea—not every point should get full ambient illumination
- Idea: Cast multiple random rays (a "distribution of rays") from each rendered surface point to estimate percent of sky hemisphere that is visible
 - Limit length of rays so distant objects have no effect
 - Cosine weighting/distribution for foreshortening
- Developers of this idea won a technical Oscar in 2010





Ambient Occlusion: Example





Ambient Occlusion: Example



